

Suba 17

- [illegible]

8. Manual wrench according to Claim 7, characterized in that the display is mechanically activatable.
9. Manual wrench according to one of the foregoing claims characterized by an electrical sensor which generates a signal when the specified tightening torque is obtained.
10. Manual wrench according to Claim 9, characterized by an electronic circuit which is effectively connected with the sensor, the circuit activating an acoustic and/or visual display when the predetermined number of driving operations implemented with a specified tightening torque is obtained.
11. Manual wrench according to Claim 9 or Claim 10, characterized by an electronic circuit which is effectively connected with a sensor, the circuit activating an acoustic and/or visual display when a signal is received from the sensor.
12. Manual wrench according to Claims 8 through 11, characterized in that the display is located at head (1).
13. Manual wrench according to one of the foregoing claims, characterized in that the manual wrench has an elongate design as a rod-type wrench.
14. Manual wrench according to one of the foregoing claims, characterized in that a flat output means is located at head (1).
15. Manual wrench according to one of the foregoing claims, characterized in that the manual wrench is equipped with a wireless power supply for the motor.
16. Manual wrench according to one of the foregoing claims characterized by a tubular housing accommodating the motor and drive train, which housing is designed with high bending strength, which bending strength during manipulation of the wrench allows for the transmission of considerably higher tightening torques to the driving operation than from the motor drive, with the rod-shaped housing having a grip area for manual actuation of the manual wrench.

17. Manual wrench according to Claim 16, characterized in that the housing consists of metal.

18. Manual wrench according to Claim 17, characterized in that the housing consists of light metal.

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